PRISM – An Overview



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PRISM – Overview

Probabilistic Symbolic Model Checker

formal analysis of probabilistic systems

Developed:

- at the University of Birmingham
- for the past 4½ years
- by: M. Kwiatkowska, G. Norman, D. Parker
- also: J. Meyer-Kayser, S. Gilmore, A. Hinton, R. Downing

PRISM – Supported Models

Discrete-time Markov chains (DTMCs) discrete state transition probabilities

Continuous-time Markov chains (CTMCs) time modelled as exponential distributions

Markov decision processes (MDPs) nondeterminism + probabilities e.g. distributed probabilistic systems

PRISM – Specification Formalisms

Extensions of temporal logic CTL

PCTL (for properties of DTMCs, MDPs) "Prob. of leader eventually being elected is 1" "Prob. of error occuring within k steps is < 0.01"</p>

CSL (for properties of CTMCs)

"Prob. of queue being full within 1 hour is < 0.2" "Long-run prob. of server being down is < 0.05"

PRISM – Basic Functionality

Parse model description (PRISM language) Construct probabilistic model Compute reachable/deadlock states

Parse properties (temporal logic) Model check each property Return Yes/No + actual probability

Recent Extensions

Process algebra operators added

More flexible parallel composition

Translation from stochastic process algebra PEPA

Support for rewards/costs added

State-based rewards/costs in probabilistic models

Verification of properties such as

"Expected number of steps before termination is..."

"Expected time to elect a leader is..."

The PRISM Language

State-based model description language based on Reactive Modules [Alur, Henzinger] Basic ingredients:

modules with local, integer-valued variables
defined by guarded commands
combine through parallel composition

Also:

synchronisation over action labels (CSP-style) global variables

Example

Randomised self-stabilisation [Israeli-Jalfon]

Ring of identical processes, each has a token

Stable state - only one process has a token

Compute:

minimum probability of stabilising maximum expected time to stabilise

```
// Israeli-Jalfon algorithm
// dxp/gxn 10/06/02
//ring of size 3
```

nondeterministic

```
global q1 : [0..1] init 1;
global q2 : [0..1] init 1;
global q3 : [0..1] init 1;
```

module start

```
start : [0..1] init 0;
// ond of initiation those
```

```
// end of initilization phase
[] start=0 -> start'=1;
```

endmodule

module process1

```
// the protocol
[] start=1 & (q1=1) -> 0.5 : q1'=0 & q3'=1 + 0.5 : q1'=0 & q2'=1;
   bits)
  to value of
// initialization (non-deterministic choice as
[] start=0 -> q1'=0;
[] start=0 -> q1'=1;
```

endmodule

```
// add further processes through renaming
module process2=process1[q1=q2, q2=q3, q3=q1] endmodule
module process3=process1[q1=q3, q2=q1, q3=q2] endmodule
```

PEPA Extension

Module parallel composition alternatives:

 $P_1 || P_2$

synchronise over alphabets

 P_1 [[a,b,c]] P_2

synchronise over a named set of actions

P₁ ||| P₂

fully asynchronous

Action hiding: P \ {a,b,c}

Case Studies

Randomised distributed algorithms/protocols

- Leader election algorithms
- **Consensus protocol**
- Byzantine agreement protocol
- IEEE 1394 FireWire Root Contention
- Crowds (anonymity) protocol
- IEEE 802.11 Wireless LAN

CTMC models

queues, networks, manufacturing systems

Implementation

Java – User interfaces, high-level code C++ – underlying data structures/engines

CUDD – BDD/MTBDD library JavaCC – language parsers

Source code – GPL, web site download Platforms – Solaris, Linux, ...

Future Plans

Simulator

GUI development

Parallel/distributed implementations

Abstraction, compositionality, ...